

**ELE539A: Optimization of Communication Systems**  
**Lecture 15: Semidefinite Programming,**  
**Detection and Estimation Applications**

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March 14, 2007

## Lecture Outline

- Cones and dual cones
- Generalized inequality and convexity
- Conic programming
- Semidefinite programming (SDP)
- Application: ML estimation
- Application: Covariance estimation
- Application: Multi-user detection

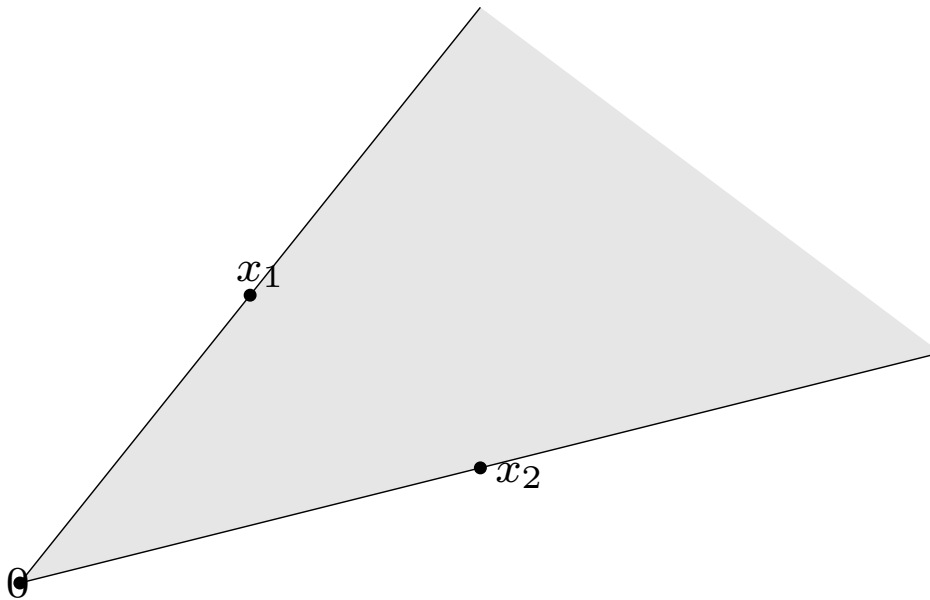
**Thanks:** Stephen Boyd (Some materials from Boyd and Vandenberghe)

## Cones and Convex Cones

$C$  is a **cone** if for every  $x \in C$  and  $\theta \geq 0$ , we have  $\theta x \in C$

$C$  is a **convex cone** if it is convex and a cone: for any  $x_1, x_2 \in C$  and  $\theta_1, \theta_2 \geq 0$

$$\theta_1 x_1 + \theta_2 x_2 \in C$$



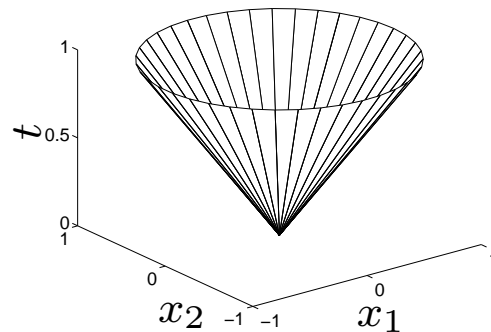
## Norm Cones

Given a norm, **norm cone** is a convex cone:

$$C = \{(x, t) \in \mathbf{R}^{n+1} \mid \|x\| \leq t\}$$

Example: **second order cone**:

$$\begin{aligned} C &= \{(x, t) \in \mathbf{R}^{n+1} \mid \|x\|_2 \leq t\} \\ &= \left\{ \begin{bmatrix} x \\ t \end{bmatrix} \mid \begin{bmatrix} x \\ t \end{bmatrix}^T \begin{bmatrix} I & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} x \\ t \end{bmatrix} \leq 0, t \geq 0 \right\} \end{aligned}$$



## Positive Semidefinite Cone

Matrix  $A \in \mathbf{R}^{n \times n}$  is **positive semidefinite**  $A \succeq 0$  if for all  $x \in \mathbf{R}^n$ ,

$$x^T A x \geq 0$$

Matrix  $A \in \mathbf{R}^{n \times n}$  is **positive definite**  $A \succ 0$  if for all  $x \in \mathbf{R}^n$ ,

$$x^T A x > 0$$

Set of symmetric positive semidefinite matrices:

$$\mathbf{S}_+^n = \{X \in \mathbf{R}^{n \times n} \mid X = X^T, X \succeq 0\}$$

$\mathbf{S}_+^n$  is a **convex cone**: if  $\theta_1, \theta_2 \geq 0$  and  $A, B \in \mathbf{S}_+^n$ , then  $\theta_1 A + \theta_2 B \in \mathbf{S}_+^n$ , since for all  $x \in \mathbf{R}^n$ :

$$x^T (\theta_1 A + \theta_2 B) x = \theta_1 x^T A x + \theta_2 x^T B x \geq 0$$

## Proper Cones and Generalized Inequalities

A cone  $K$  is a **proper cone** if

- $K$  is convex
- $K$  is closed
- $K$  has nonempty interior
- $K$  has no lines ( $x \in K, -x \in K \Rightarrow x = 0$ )

Proper cone  $K$  induces a **generalized inequality** (**partial ordering** on  $\mathbf{R}^n$ ):

$$x \preceq_K y \iff y - x \in K$$

$$x \prec_K y \iff y - x \in \mathbf{int} K$$

## Examples

- Nonnegative orthant and componentwise inequality:

$K = \mathbf{R}_+^n$  is a proper cone

$x \preceq_K y$  means  $x_i \leq y_i, i = 1, \dots, n$

$x \prec_K y$  means  $x_i < y_i, i = 1, \dots, n$

- Positive semidefinite cone and matrix inequality:

$K = \mathbf{S}_+^n$  is a proper cone in the set of symmetric matrices  $\mathbf{S}^n$

$X \preceq_K Y$  means  $Y - X$  is positive semidefinite

$X \prec_K Y$  means  $Y - X$  is positive definite.

## Properties of Generalized Inequalities

- If  $x \preceq_K y$  and  $u \preceq_K v$ , then  $x + u \preceq_K y + v$
- If  $x \preceq_K y$  and  $y \preceq_K z$ , then  $x \preceq_K z$
- If  $x \preceq_K y$  and  $\alpha \geq 0$ , then  $\alpha x \preceq_K \alpha y$
- If  $x \preceq_K y$  and  $y \preceq_K x$ , then  $x = y$
- If  $x_i \preceq_K y_i$  for  $i = 1, \dots$ , and  $x_i \rightarrow x$  and  $y_i \rightarrow y$  as  $i \rightarrow \infty$ , then  $x \preceq_K y$



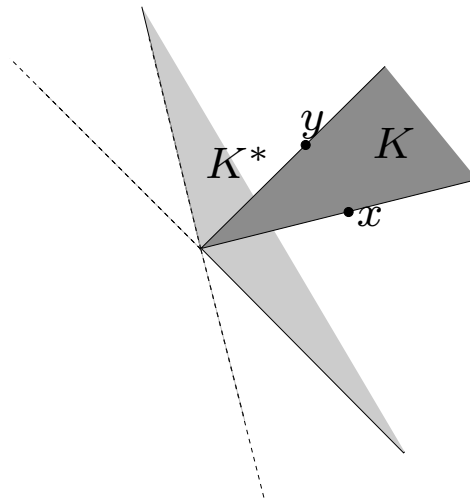
## Dual Cones

Given a cone  $K$ . Dual cone of  $K$ :

$$K^* = \{y \mid x^T y \geq 0 \forall x \in K\}$$

$K^*$  is **always** a convex cone

$K$  is proper cone  $\Rightarrow K^*$  is a proper cone and  $K^{**} = K$



- Nonnegative orthant cone is self-dual

## Dual PSD Cone

Consider inner product  $X^T Y = \mathbf{tr}(XY) = \sum_{i,j} X_{ij} Y_{ij}$  on  $\mathbf{S}^n$ . PSD cone  $\mathbf{S}_+^n$  is self-dual:

$$\mathbf{tr}(XY) \geq 0 \quad \forall X \succeq 0 \Leftrightarrow Y \succeq 0$$

**Proof:** Forward direction: suppose  $Y \not\succeq 0$ . Then  $\exists q \in \mathbf{R}^n$  such that  $q^T Y q = \mathbf{tr}(qq^T Y) < 0$ . Therefore,  $X = qq^T$  satisfies  $\mathbf{tr}(XY) < 0$ .

Reverse direction: suppose  $X, Y \succeq 0$ . Express  $X$  by eigenvalue decomposition:  $X = \sum_{i=1}^n \lambda_i q_i q_i^T$  where  $\lambda_i \geq 0$ ,  $i = 1, \dots, n$ . Then

$$\mathbf{tr}XY = \mathbf{tr} \left( Y \sum_{i=1}^n \lambda_i q_i q_i^T \right) = \sum_{i=1}^n \lambda_i q_i^T Y q_i \geq 0$$

## Dual Generalized Inequality

Given proper cone  $K$  and generalized inequality  $\succeq_K$ . Dual cone  $K^*$  is also proper and induces dual generalized inequality  $\succeq_{K^*}$

Relationship between  $\succeq_K$  and  $\succeq_{K^*}$ :

1.  $x \preceq_K y$  iff  $\lambda^T x \leq \lambda^T y$  for all  $\lambda \succeq_{K^*} 0$
2.  $x \prec_K y$  iff  $\lambda^T x < \lambda^T y$  for all  $\lambda \succeq_{K^*} 0, \lambda \neq 0$

Since  $K^{**} = K$ , these properties hold if  $\succeq_K$  and  $\succeq_{K^*}$  are interchanged

## Generalized Inequality Induced Monotonicity

$f : \mathbf{R}^n \rightarrow \mathbf{R}$  is  $K$ -nondecreasing (increasing) if

$$x \preceq_K y \Rightarrow f(x) \leq (<) f(y)$$

First order condition for differentiable  $f$  with convex domain:  $f$  is  $K$ -nondecreasing iff:

$$\nabla f(x) \succeq_{K^*} 0$$

$f$  is  $K$ -increasing if:

$$\nabla f(x) \succ_{K^*} 0$$

Example: For PSD cone,  $\mathbf{tr}(X^{-1})$  is matrix decreasing on  $\mathbf{S}_{++}^n$  and  $\det X$  is matrix increasing on  $\mathbf{S}_+^n$

## Generalized Inequality Induced Convexity

$f : \mathbf{R}^n \rightarrow \mathbf{R}^m$  is  $K$ -convex if for all  $x, y$  and  $\theta \in [0, 1]$ ,

$$f(\theta x + (1 - \theta)y) \preceq_K \theta f(x) + (1 - \theta)f(y)$$

$f : \mathbf{R}^n \rightarrow \mathbf{R}^m$  is strictly  $K$ -convex if for all  $x \neq y$  and  $\theta \in (0, 1)$ ,

$$f(\theta x + (1 - \theta)y) \prec_K \theta f(x) + (1 - \theta)f(y)$$

**First order condition:** For differentiable  $f$  with convex domain,  $f$  is  $K$ -convex iff for all  $x, y \in \mathbf{dom} f$ ,

$$f(y) \succeq_K f(x) + Df(x)(y - x)$$

## Matrix Convexity

$f$  is a symmetric-matrix-valued function.  $f : \mathbf{R}^{n \times m} \rightarrow \mathbf{S}^m$ .  $f$  is convex with respect to matrix inequality if for any  $x, y \in \mathbf{dom} f$  and  $\theta \in [0, 1]$ ,

$$f(\theta x + (1 - \theta)y) \preceq \theta f(x) + (1 - \theta)f(y)$$

Equivalently,  $f$  is **matrix convex** iff scalar-valued function  $z^T f(x) z$  is convex for all  $z$

- $f(X) = XX^T$  is matrix convex
- $f(X) = X^p$  is matrix convex for  $p \in [1, 2]$  or  $p \in [-1, 0]$ , and matrix concave for  $p \in [0, 1]$
- $f(X) = e^X$  is not matrix convex (unless  $X$  is a scalar)

## Generalized Inequality Constraints

Convex optimization with **generalized inequality constraints** on vector-valued functions:

$$\begin{array}{ll} \text{minimize} & f_0(x) \\ \text{subject to} & f_i(x) \preceq_{K_i} 0, \quad i = 1, 2, \dots, m \end{array}$$

$f_0 : \mathbf{R}^n \rightarrow \mathbf{R}$ ,  $f_i : \mathbf{R}^n \rightarrow \mathbf{R}^{k_i}$  are  $K_i$ -convex for some proper cones  $K_i$

- Feasible set is convex
- Local optimality  $\Rightarrow$  global optimality

## Conic Programming

Linear programming with linear generalized inequality constraint:

$$\begin{aligned} & \text{minimize} && c^T x \\ & \text{subject to} && Fx + G \preceq_K 0 \\ & && Ax = b \end{aligned}$$

- When  $K$  is nonnegative orthant, conic program reduces to LP
- When  $K$  is PSD cone, write inequality constraints as **Linear Matrix Inequalities** (LMI):

$$x_1 F_1 + \dots + x_n F_n + G \preceq 0$$

where  $F_i, G \in \mathbf{S}^k$ . When they are diagonal, LMI reduces to linear inequalities



## SDP

**SDP**: Minimize linear objective over linear equalities and LMI on variables  $x \in \mathbf{R}^n$

$$\begin{aligned} & \text{minimize} && c^T x \\ & \text{subject to} && x_1 F_1 + \dots + x_n F_n + G \preceq 0 \\ & && Ax = b \end{aligned}$$

**SDP in standard form**: Minimize a matrix inner product over equality constraints on inner products on variables  $X \in \mathbf{S}^n$

$$\begin{aligned} & \text{minimize} && \mathbf{tr}(CX) \\ & \text{subject to} && \mathbf{tr}(A_i X) = b_i, \quad i = 1, 2, \dots, p \\ & && X \succeq 0 \end{aligned}$$

## LP and SOCP as SDP

LP as SDP:

$$\begin{aligned} & \text{minimize} && c^T x \\ & \text{subject to} && \mathbf{diag}(Gx - h) \preceq 0 \\ & && Ax = b \end{aligned}$$

SOCP:

$$\begin{aligned} & \text{minimize} && c^T x \\ & \text{subject to} && \|A_i x + b_i\|_2 \leq c_i^T x + d_i, \quad i = 1, \dots, N \\ & && Fx = g \end{aligned}$$

SOCP as SDP:

$$\begin{aligned} & \text{minimize} && c^T x \\ & \text{subject to} && \begin{bmatrix} (c_i x + d_i)I & A_i x + b_i \\ (A_i x + b_i)^T & (c_i x + d_i)I \end{bmatrix} \succeq 0, \quad i = 1, \dots, N \\ & && Fx = g \end{aligned}$$

## Matrix Norm Minimization

$A(x) = A_0 + x_1 A_1 + \dots + x_n A_n$  where  $A_i \in \mathbf{R}^{p \times q}$ . Consider unconstrained spectral norm (max. singular value) minimization over  $x$ :

$$\text{minimize } \|A(x)\|_2$$

which is equivalent to convex optimization with LMI on  $(x, t)$

$$\begin{aligned} &\text{minimize } t \\ &\text{subject to } A(x)^T A(x) \preceq t^2 I \end{aligned}$$

which is equivalent to SDP

$$\begin{aligned} &\text{minimize } t \\ &\text{subject to } \begin{bmatrix} tI & A(x) \\ A(x)^T & tI \end{bmatrix} \succeq 0 \end{aligned}$$

## Related Problems

### SDP problems:

- Minimize largest eigenvalue
- Minimize sum of  $r$  largest eigenvalues
- Maximize log determinant

### SDP approximations:

- Combinatorial optimization
- Rank minimization

## ML Estimation

Estimate  $x \in \mathbf{R}^n$  from a set of measurements  $y \in \mathbf{R}^m$ :

$$y_i = a_i^T x + v_i, \quad i = 1, \dots, m$$

where  $v_i$  are i.i.d. noise with distribution  $p$  on  $\mathbf{R}$

By independence, **likelihood function** is

$$\prod_{i=1}^m p(y_i - a_i^T x)$$

**Maximum Likelihood estimate** is any optimal point for the problem in  $x$ :

$$\text{maximize } \sum_{i=1}^m \log p(y_i - a_i^T x)$$

Since many distributions are log-concave, the above problem are often convex optimization

## Examples

- **Gaussian noise:**  $v_i$  are Gaussian with zero mean and variance  $\sigma^2$ :

$$p(z) = (2\pi\sigma^2)^{-1/2} \exp(-z^2/2\sigma^2)$$

Log-likelihood function:  $-(1/2) \log(2\pi\sigma) - (1/2\sigma^2) \|Ax - y\|_2^2$

$$\hat{x} = \underset{x}{\operatorname{argmin}} \|Ax - y\|_2$$

where rows of  $A$  are  $a_i^T$ . Solution of **least-squares**

- **Laplacian noise:**  $v_i$  are Laplacian:  $p(z) = (1/2a) \exp(-|z|/a)$ ,  $a > 0$

$$\hat{x} = \underset{x}{\operatorname{argmin}} \|Ax - y\|_1$$

Solution of  **$l - 1$  norm minimization**

## Covariance Estimation for Gaussian Distribution

$y \in \mathbf{R}^n$  is **multivariate Gaussian** with zero mean and covariance matrix  $R = \mathbf{E} yy^T \in \mathbf{S}_{++}^n$  with distribution:

$$p_R(y) = (2\pi)^{-n/2} \det(R)^{-1/2} \exp(-y^T R^{-1} y/2)$$

Goal: **estimate covariance**  $R$  based on  $N$  i.i.d. **samples**  $y_1, \dots, y_N \in \mathbf{R}^n$

Sample covariance matrix

$$Y = \frac{1}{N} \sum_{k=1}^N y_k y_k^T$$

**Log likelihood function**  $\log p_R(y_1, \dots, y_N)$  **not** concave in  $R$ :

$$l(R) = -(Nn/2) \log(2\pi) - (N/2) \log \det R - (N/2) \mathbf{tr}(R^{-1} Y)$$

**Information matrix**  $S = R^{-1}$ , log likelihood function is **concave** in  $S$ :

$$l(S) = -(Nn/2) \log(2\pi) + (N/2) \log \det S - (N/2) \mathbf{tr}(SY)$$

## Covariance Estimation for Gaussian Distribution

ML estimate of  $S$  found by solving [convex optimization](#):

$$\begin{aligned} & \text{maximize} && \log \det S - \mathbf{tr}(SY) \\ & \text{subject to} && S \in \mathcal{S}, S \succeq 0 \end{aligned}$$

where  $\mathcal{S}$  is a [convex constraint set](#) of  $S$  based on prior information about  $R$

*e.g.*, bounds on  $R$ :  $L \preceq R \preceq U$  ( $U^{-1} \preceq S \preceq L^{-1}$ )

*e.g.*, condition number constraint on  $R$ :  $\lambda_{\max}(R) \leq \kappa_{\max} \lambda_{\min}(R)$   
( $uI \preceq S \preceq \kappa_{\max} uI$ , variables:  $(S, u)$ )



## Multi-user Detection

Received signal of  $K$ -user basic synchronous CDMA channel:

$$y(t) = \sum_{k=1}^K A_k b_k s_k(t) + n(t), \quad t \in [0, T]$$

Amplitude  $A_k$ , signature waveform  $s_k(t)$ , information bit  $b_k \in \{-1, +1\}$ , noise  $n(t)$ , period  $T$

ML detection: find  $b$  that minimizes

$$\begin{aligned} & \int_0^T \left[ y(t) - \sum_{k=1}^K A_k b_k s_k(t) \right]^2 dt \\ &= \int_0^T \left[ \sum_{k=1}^K A_k b_k s_k(t) \right] dt - 2 \int_0^T \left[ \sum_{k=1}^K A_k b_k s_k(t) \right] y(t) dt \\ &= b^T H b - 2b^T A y \end{aligned}$$

## Boolean Constrained QP Formulation

$A = \mathbf{diag}(A)$ : amplitude matrix

$R_{ij} = \int_0^T s_i(t)s_j(t)dt$ : cross-correlation matrix

$y = RA b + n$ : sampled matched filter output

Notation:  $H = ARA$  and  $p = -2Ay$

$$\begin{aligned} &\text{minimize} && x^T H x + p^T x \\ &\text{subject to} && x_i \in \{-1, +1\}, \quad i = 1, \dots, K \end{aligned}$$

Equivalent form: let  $X = x x^T$

$$\begin{aligned} &\text{subject to} && X_{ii} = 1, \quad i = 1, \dots, K, \\ &&& X \succeq 0, \quad \text{rank}(X) = 1 \end{aligned}$$

## SDP Relaxation

Neglect rank constraint:

$$\begin{aligned} \text{subject to } & X_{ii} = 1, \quad i = 1, \dots, K, \\ & X \succeq 0 \end{aligned}$$

$$\text{Let } \hat{X} = \begin{bmatrix} xx^T & x \\ x^T & 1 \end{bmatrix} \text{ and } C = \begin{bmatrix} H & p/2 \\ p^T/2 & 1 \end{bmatrix}, \text{ reformulate as SDP:}$$

$$\begin{aligned} \text{minimize } & \text{tr}(C\hat{X}) \\ \text{subject to } & \hat{X}_{ii} = 1, \quad i = 1, \dots, K + 1, \\ & \hat{X} \succeq 0 \end{aligned}$$

Factorization and randomization methods to recover solution to original boolean constrained QP from SDP relaxation solutions

## Dual Relaxation

Relax  $x^T x = K$  to  $x^T x \leq K$ :

$$\begin{aligned} & \text{minimize} && x^T H x + p^T x \\ & \text{subject to} && x^T x \leq K \end{aligned}$$

Lagrange dual problem:

$$\begin{aligned} & \text{minimize} && -\frac{1}{4} p^T (H + \lambda I)^{-1} p - \lambda K \\ & \text{subject to} && \lambda \geq 0 \end{aligned}$$

Gradient-descent method solves this convex optimization in **one** variable  $\lambda$

Recover **primal optimal solution**:  $x^* = (H + \lambda^* I)^{-1} A y$

## Complexity Performance Tradeoff

Exhaustive search: NP-hard  $\mathcal{O}(2^K)$

Successive interference cancellation

Relaxation methods:

- SDP relaxation: polynomial time  $\mathcal{O}(K^3)$  (SDP solution dominates randomization in terms of computational load)
- Unconstrained relaxation: analytic solution (related to decorrelator and linear MMSE)
- Bound relaxation
- Dual relaxation

Better complexity-tradeoff possible through duality, randomization, and other relaxation methods?

## Lecture Summary

- Proper cones induce generalized inequalities in  $\mathbf{R}^n$  and  $\mathbf{S}^n$ , which induces generalized convex inequality constraints
- Convex optimization with generalized inequalities: conic programming
- SDP is a conic programming over PSD cone with LMI, includes LP, QP, QCQP, SOCP as special cases
- Relaxation for multi-user detection problems

Reading: Sections 2.1, 2.6, 3.6, 4.6, 5.9 in Boyd and Vandenberghe.

L. Vandenberghe and S. Boyd, "Semidefinite programming," *SIAM Review*, March 1996.

W. K. Ma, T. N. Davidson, K. M. Wong, Z. Q. Luo, and P. C. Ching, "Quasi-maximum-likelihood multiuser detection using semidefinite relaxation with applications to synchronous CDMA," *IEEE Trans. Signal Proc.*, vol. 50, no. 4, pp. 912-922, April 2002.